

Continuous Multiple Importance Sampling

SIGGRAPH 2020

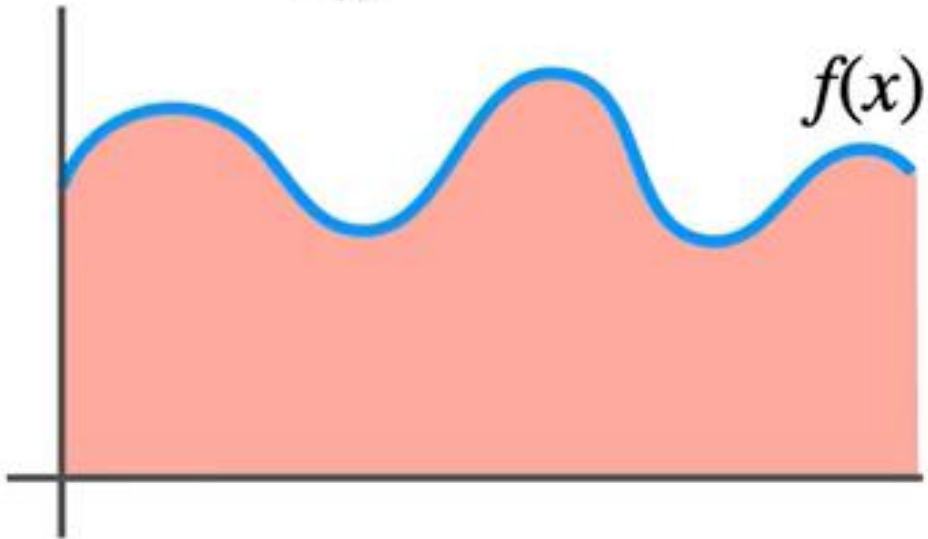
20180183 Haun Kim

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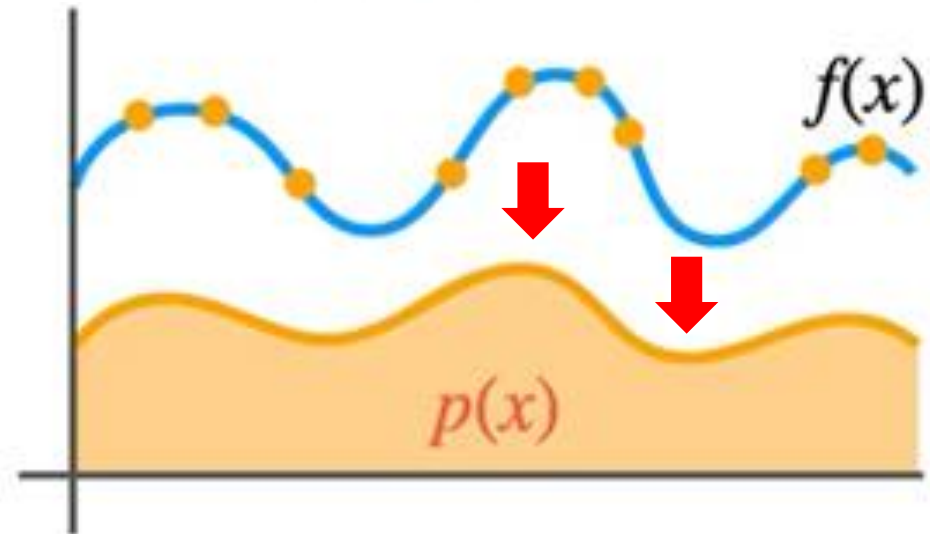
Recap - Multiple Importance Sampling

$$\int_x f(x) dx = I$$



Integration problem

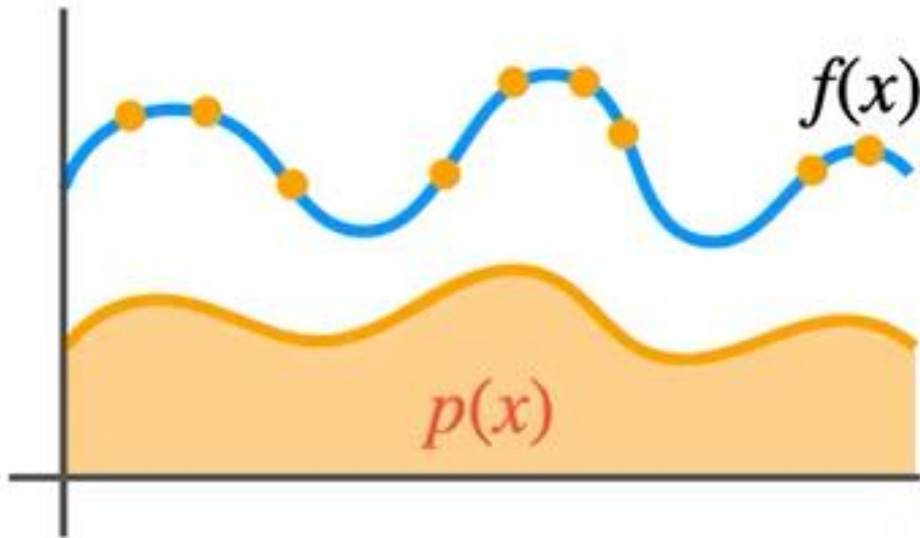
$$\frac{1}{n} \sum_{i=1}^n \frac{f(x_i)}{p(x_i)} = \langle I \rangle_n$$



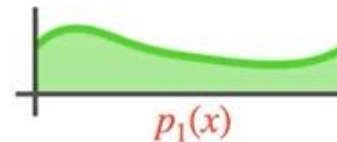
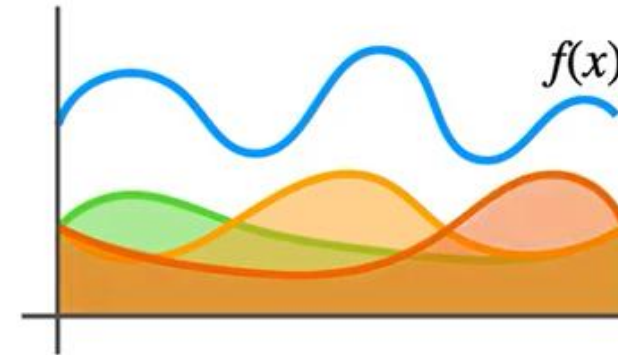
Importance Sampling

Recap - Multiple Importance Sampling

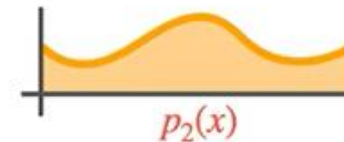
$$\frac{1}{n} \sum_{i=1}^n \frac{f(x_i)}{p(x_i)} = \langle I \rangle_n$$



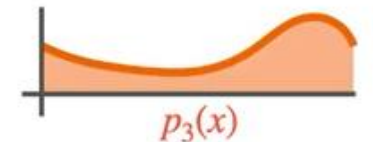
Importance Sampling



$p_1(x)$



$p_2(x)$



$p_3(x)$

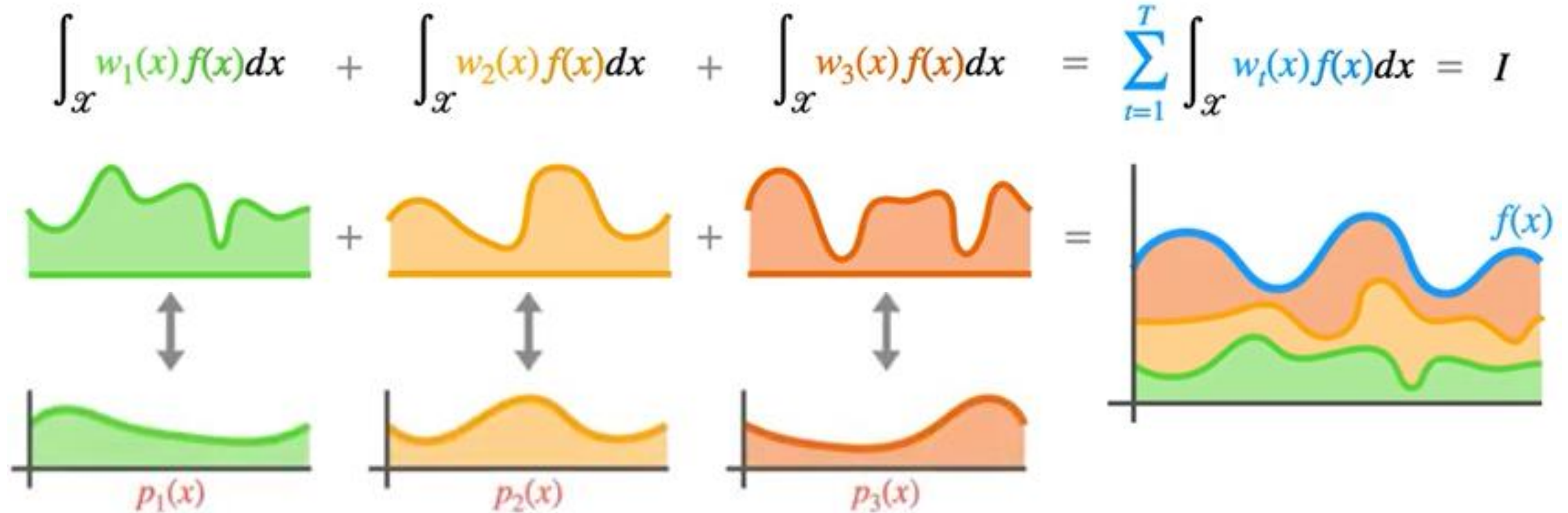
MIS

Recap - Multiple Importance Sampling

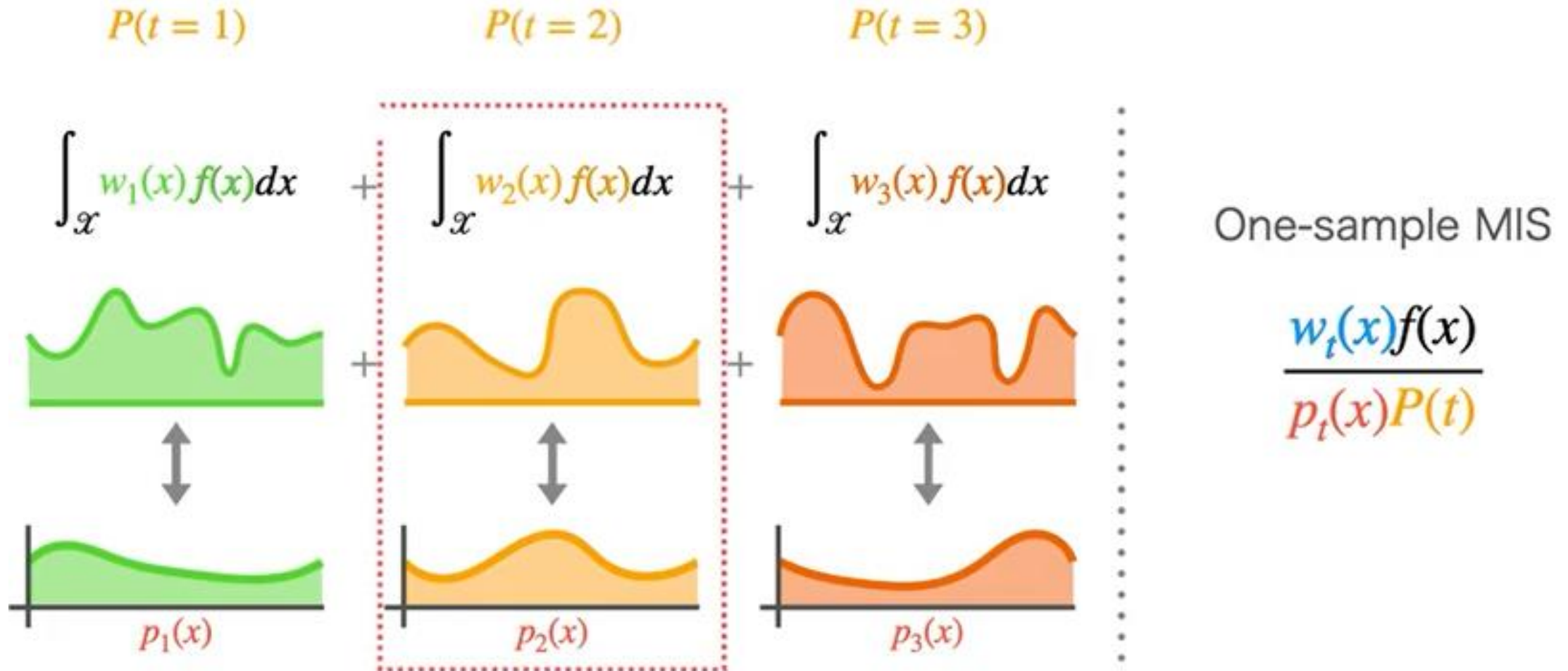
$$I = \int_{\mathcal{X}} f(x) dx$$

$$\begin{aligned} \rightarrow \int_{\mathcal{X}} \underbrace{\sum_{t=1}^T w_t(x)}_{=1} f(x) dx &\quad \rightarrow \sum_{t=1}^T \int_{\mathcal{X}} w_t(x) f(x) dx \end{aligned}$$

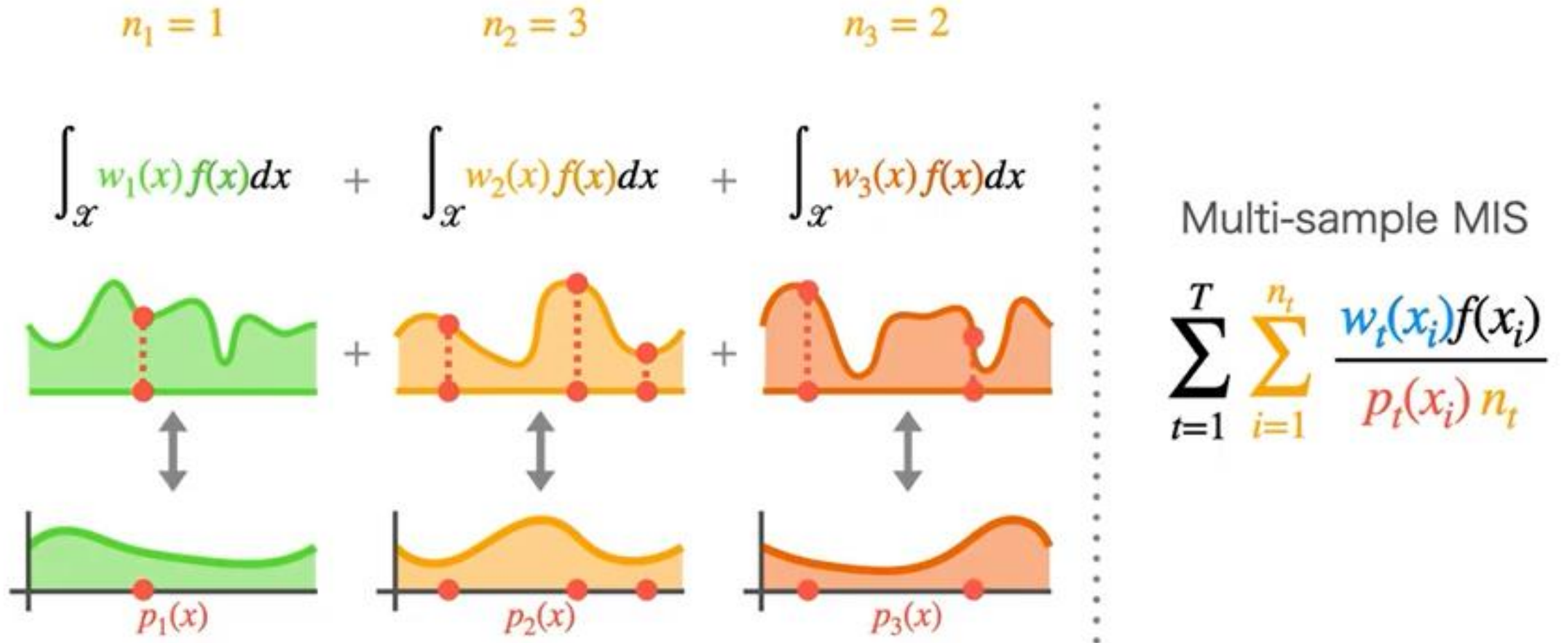
Recap - Multiple Importance Sampling



Recap - Multiple Importance Sampling



Recap - Multiple Importance Sampling



Recap – Balance Heuristic

Optimal MIS weights

THEOREM 5.2. Let the column vector $\alpha = (\alpha_1, \dots, \alpha_N)^T$ satisfy the system of linear equations

$$A\alpha = \mathbf{b}, \quad (12)$$

where A and \mathbf{b} are the technique matrix and the contribution vector, respectively. Then the weighting functions

$$w_i^o(x) = \alpha_i \frac{p_i(x)}{f(x)} + \frac{n_i p_i(x)}{\sum_{j=1}^N n_j p_j(x)} \left(1 - \frac{\sum_{j=1}^N \alpha_j p_j(x)}{f(x)} \right) \quad (13)$$

minimize the functional $V[w_1, \dots, w_N]$.

$$\langle F \rangle^o = \sum_{i=1}^N \alpha_i + \frac{1}{M} \sum_{i=1}^N \sum_{j=1}^{n_i} \left(\frac{f(X_{ij})}{p_c(X_{ij})} - \frac{\sum_{k=1}^N \alpha_k p_k(X_{ij})}{p_c(X_{ij})} \right). \quad (16)$$

One-sample MIS

$$\frac{w_t(x)f(x)}{p_t(x)P(t)}$$



$$w_t(x) = \frac{p_t(x)P(t)}{\sum_{j=1}^T p_j(x)P(j)}$$

Multi-sample MIS

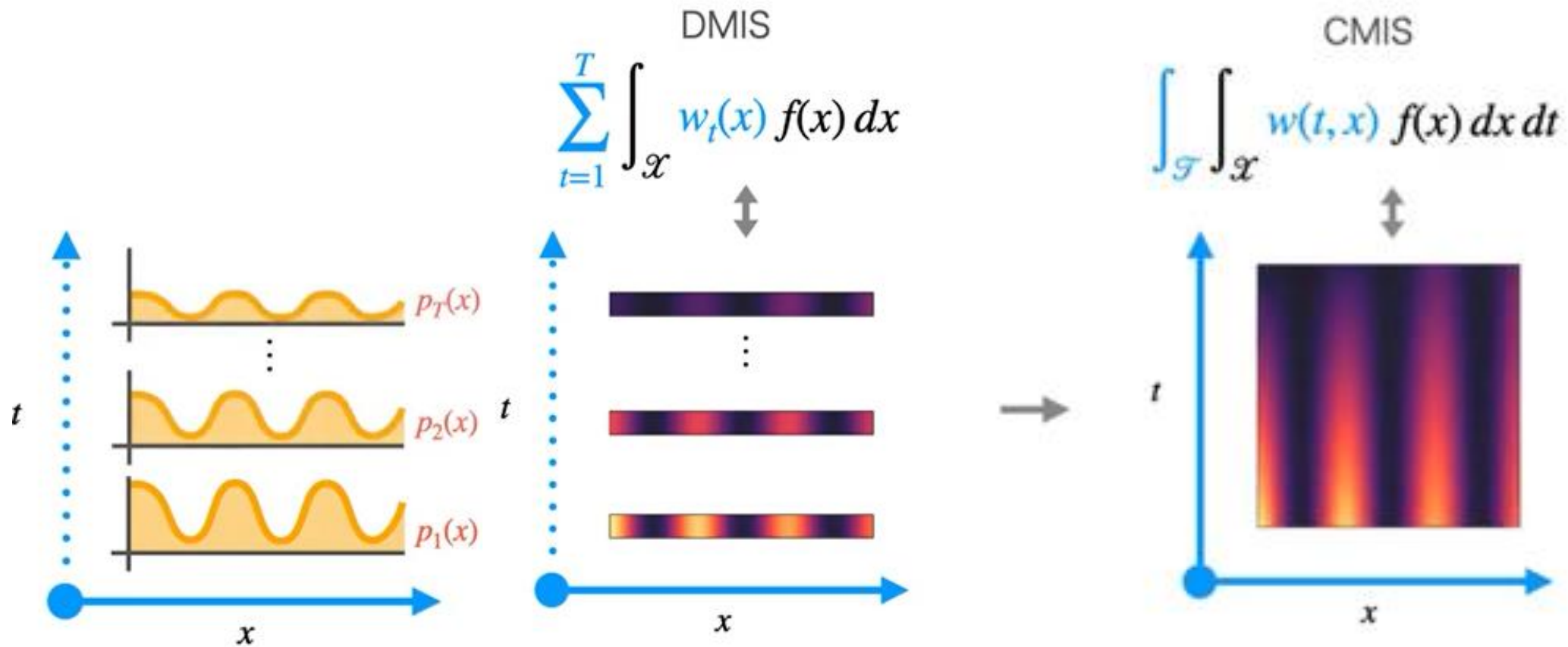
$$\sum_{t=1}^T \sum_{i=1}^{n_t} \frac{w_t(x_i)f(x_i)}{p_t(x_i)n_t}$$



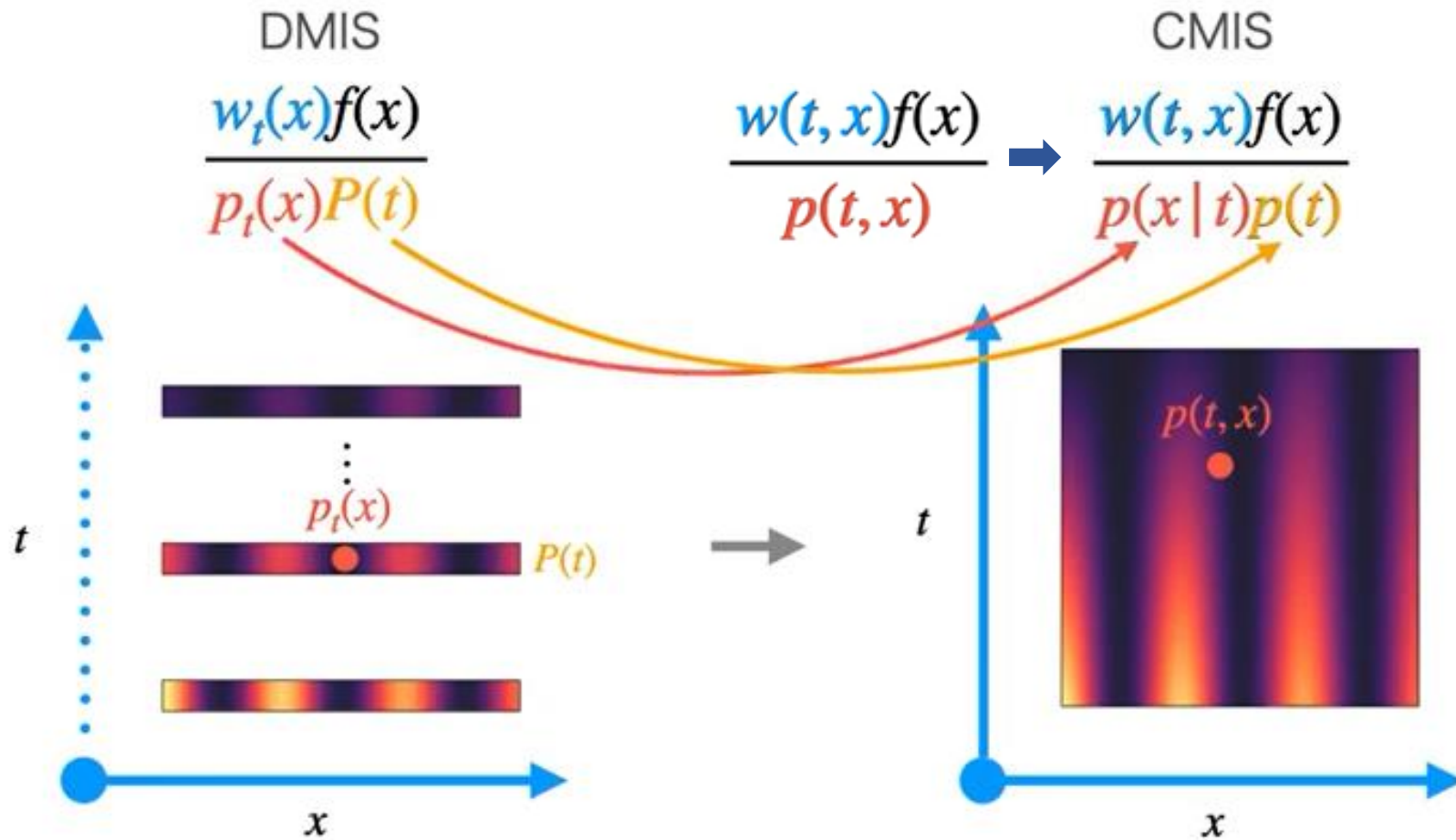
$$w_t(x) = \frac{p_t(x)n_t}{\sum_{j=1}^T p_j(x)n_j}$$

Continuous MIS

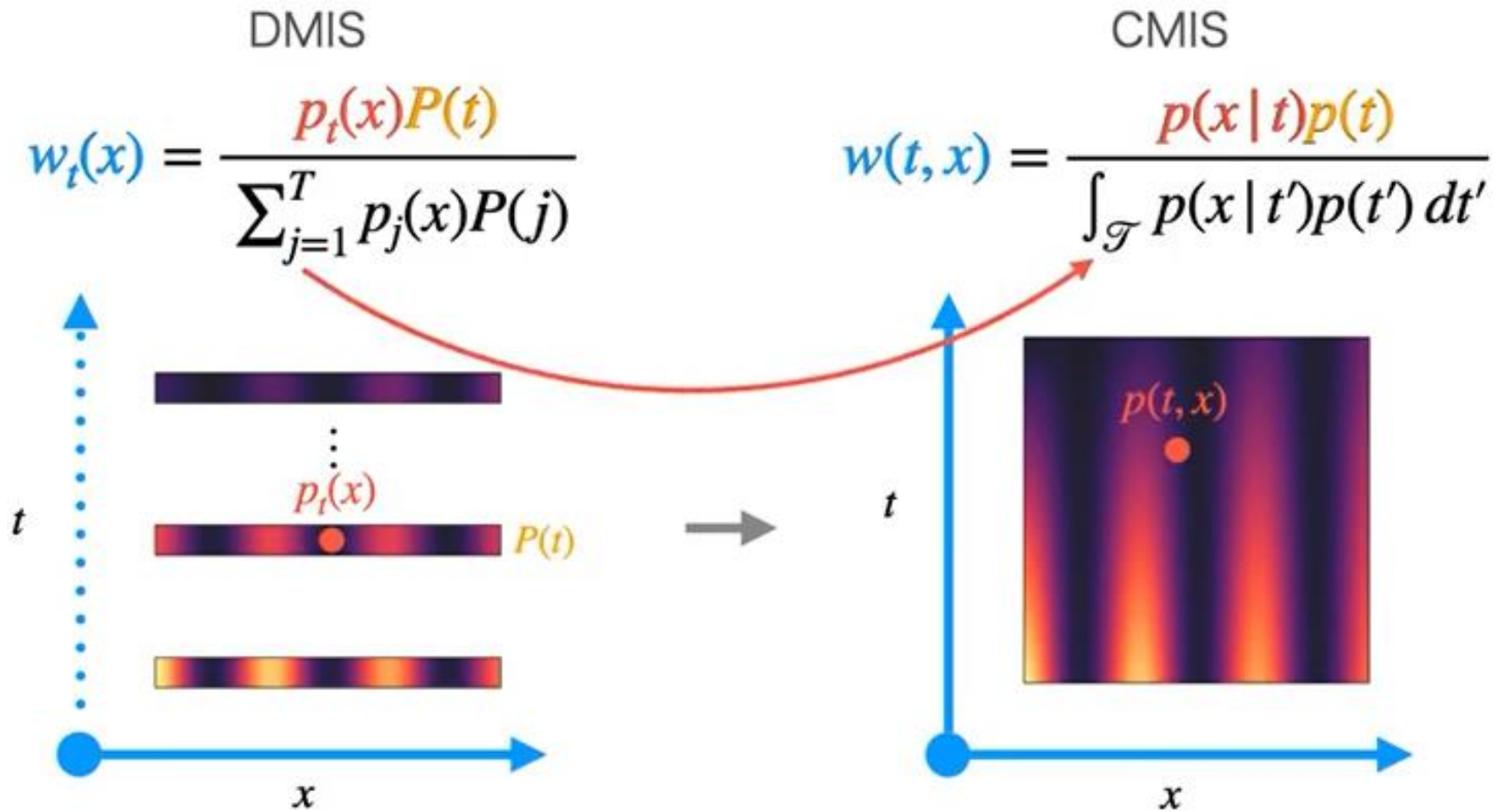
Continuous MIS



Continuous MIS – one sampling

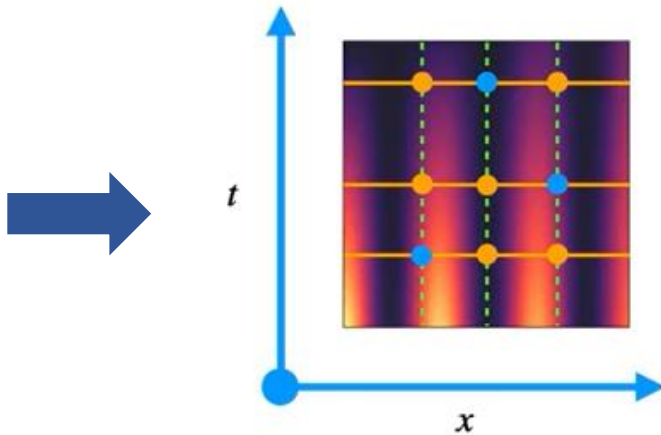


Continuous MIS – balance heuristic



Stochastic MIS

$$w(t, x) = \frac{p(x | t)p(t)}{\int_{\mathcal{G}} p(x | t')p(t') dt'}$$

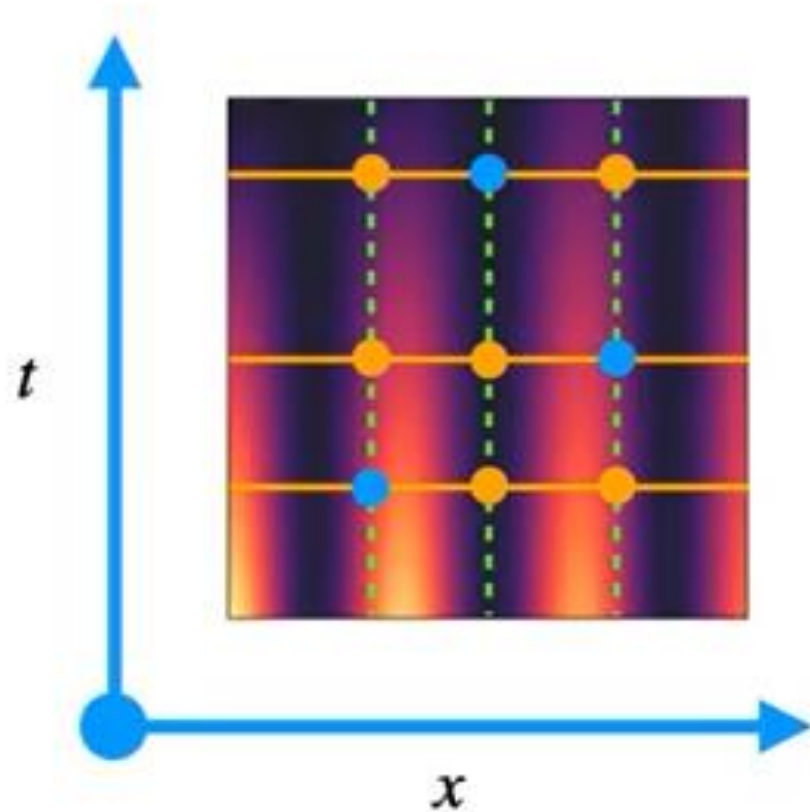


$$w(t, x) = \frac{p(x | t)p(t)}{\frac{1}{T} \sum_{j=1}^T \frac{p(x | t_j)p(t_j)}{p(t_j)}}$$



$$w(t, x) = \frac{p(x | t)p(t)}{\frac{1}{T} \sum_{j=1}^T p(x | t_j)}$$

Stochastic MIS



Stochastic MIS

One sample per technique

$$\sum_{i=1}^T \frac{p(x_i | t_i)}{\sum_{j=1}^T p(x_i | t_j)} \frac{f(x_i)}{p(x_i | t_i)}$$

Multi-sample MIS

$$\sum_{i=1}^T \sum_{j=1}^{n_i} \frac{w_t(x_j) f(x_j)}{p_t(x_j) n_t}$$

\neq

$$\downarrow$$
$$w_t(x) = \frac{p_t(x) n_t}{\sum_{j=1}^T p_j(x) n_j}$$

Application #1

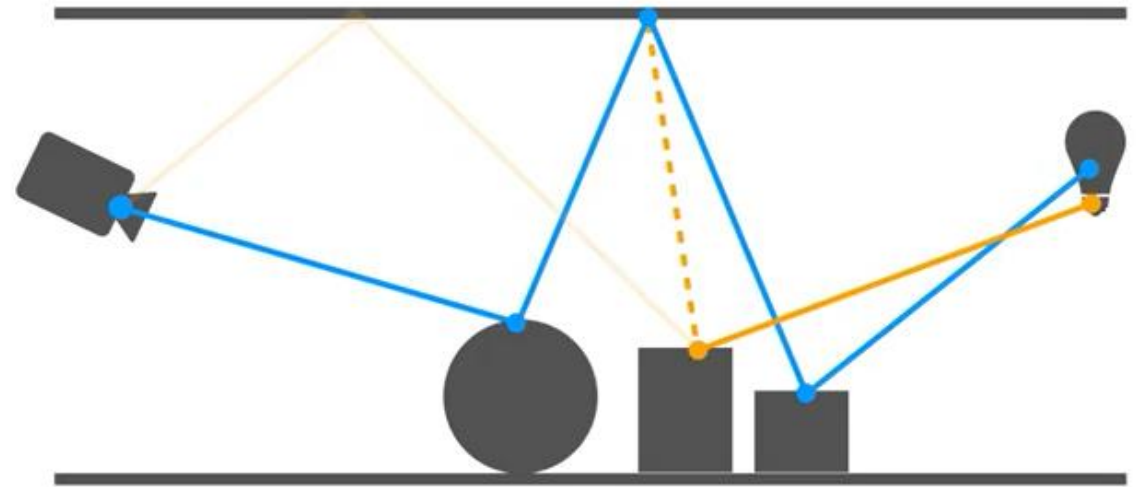
Path Reuse

Previous work – path filtering

Alexander Keller, Ken Dahm, and Nikolaus Binder. 2014. Path Space Filtering (SIGGRAPH '14).

Motive

1. To reduce noise of random sampling in path tracing, we want to sample more paths, but this can be quite expensive.
2. To reduce these costs, we use other existing paths by reconnecting

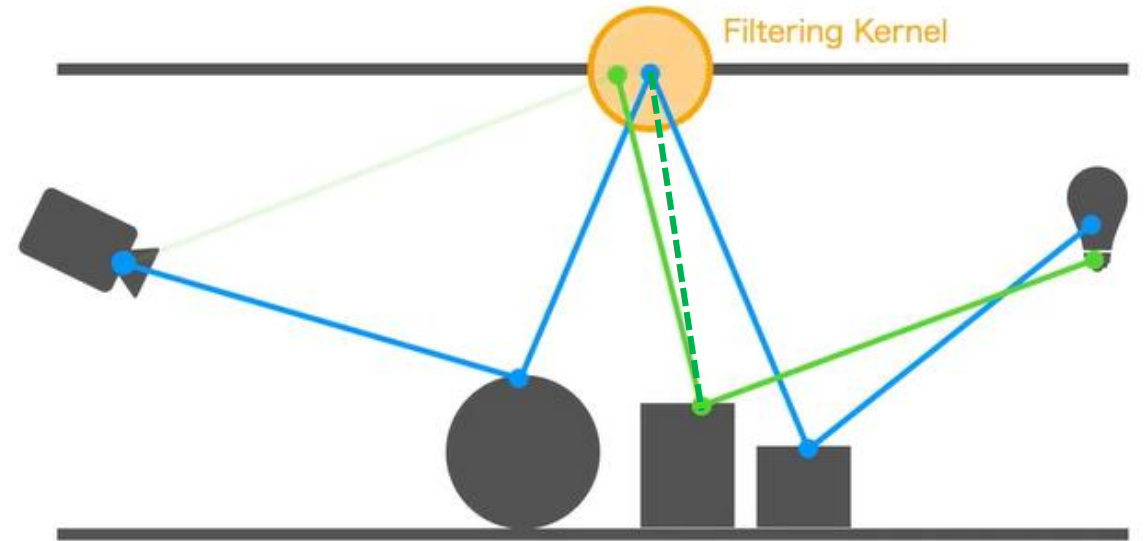


Previous work – path filtering

Alexander Keller, Ken Dahm, and Nikolaus Binder. 2014. Path Space Filtering (SIGGRAPH '14).

Algorithm

1. Generate some filtering kernels while path sampling
2. When any generated path reaches the filtering kernel, the remaining path is set to the existing path that generated that filtering kernel.



Previous work – path filtering

Alexander Keller, Ken Dahm, and Nikolaus Binder. 2014. Path Space Filtering (SIGGRAPH '14).

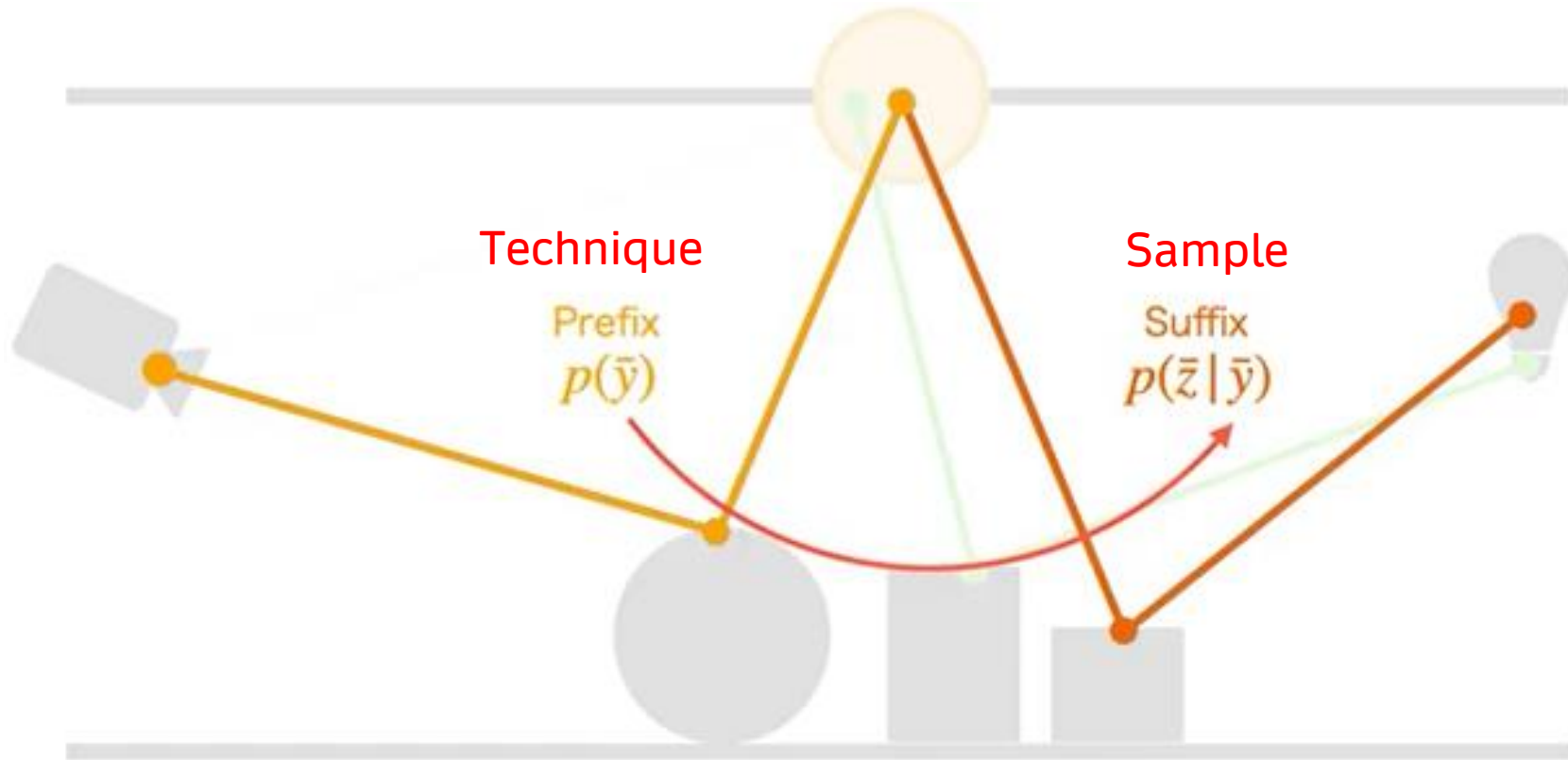
Problem

1. Bias

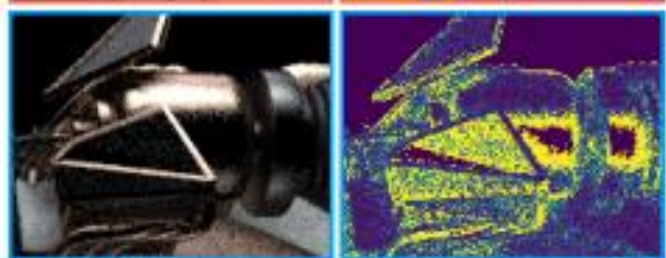
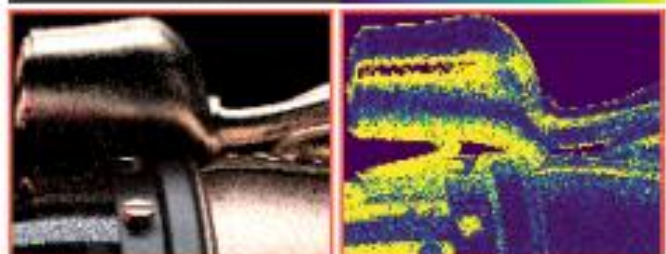
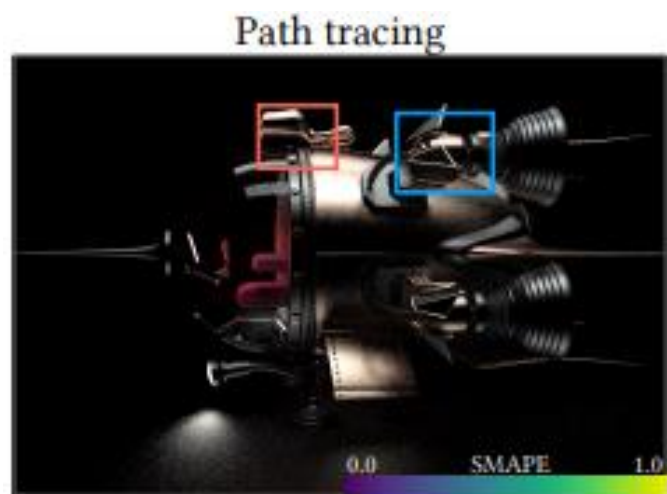
2. Works well on diffuse materials but it has some

difficulty with glossy surfaces in detail geometry

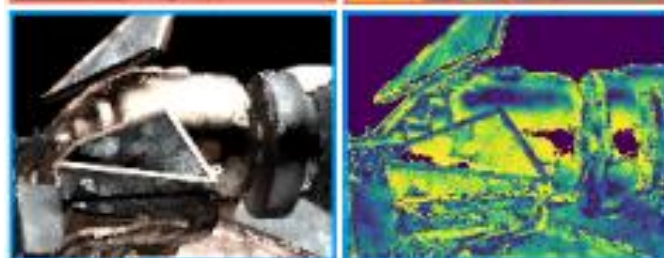
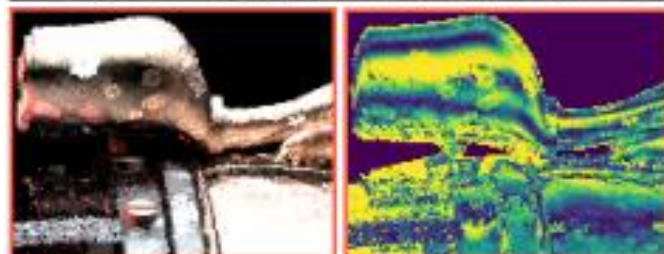
Path filtering - CMIS



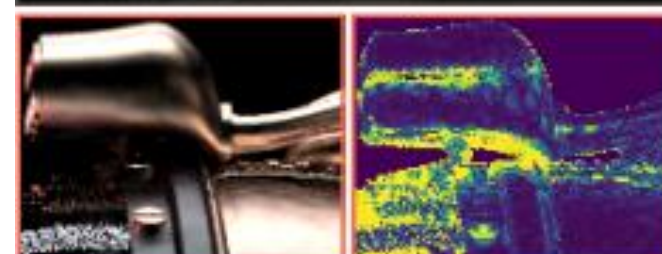
Path filtering - CMIS



115.50 sec SMAPE 0.279 (1.00x)
MSE 0.0016 (1.00x)



116.54 sec SMAPE 0.276 (0.99x)
2150.5 (1344062.5x)



116.42 sec SMAPE **0.196 (0.70x)**
0.002 (1.25x)

Application #2

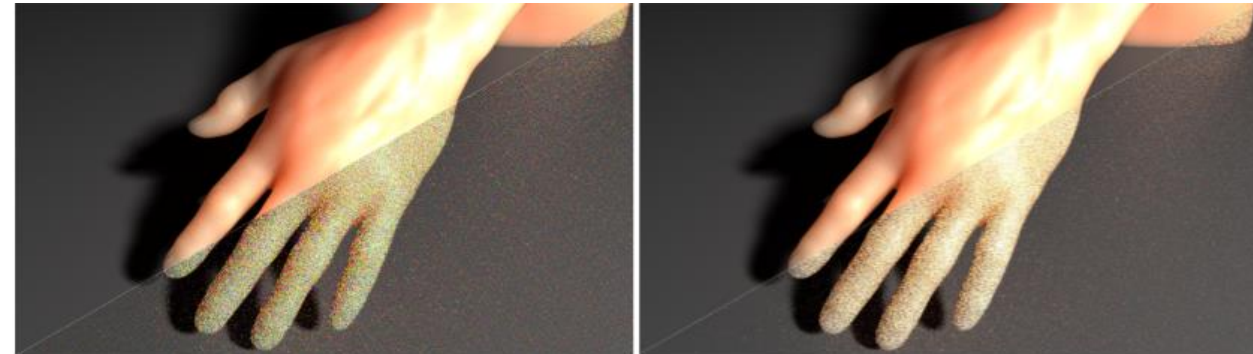
Spectral Rendering

Previous work – spectral rendering

Alexander Wilkie, Sehera Nawaz, Marc Droske, Andrea Weidlich, and Johannes Hanika. 2014. Hero Wavelength Spectral Sampling.

Motive

1. Overcome the limitations of tri-stimulus (RGB) rendering
2. Extend the path integral over the visible rays wavelength domain



Single wavelength sampling

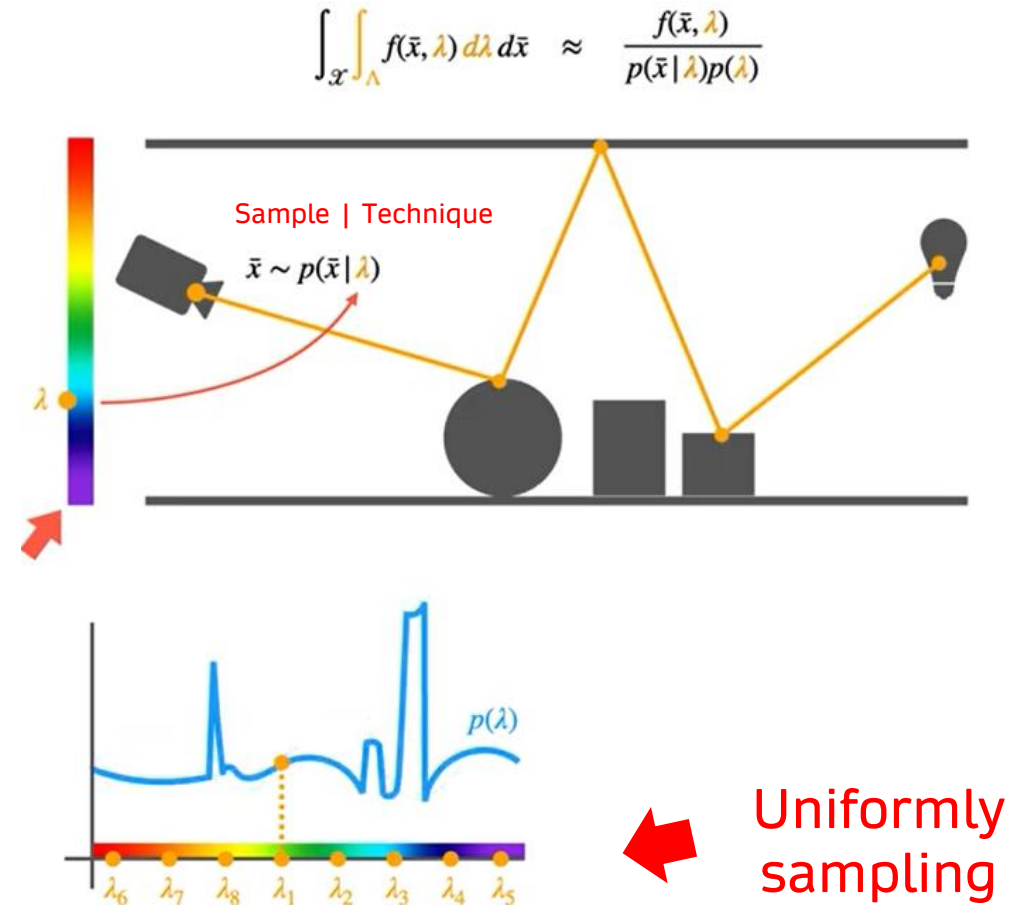
Spectral rendering

Previous work – spectral rendering

Alexander Wilkie, Sehera Nawaz, Marc Droske, Andrea Weidlich, and Johannes Hanika. 2014. Hero Wavelength Spectral Sampling.

Algorithm (Hero MIS)

1. Sample a wavelength
 2. Given a sampled wavelength, sample n wavelengths which are uniformly spaced
 3. N spectral paths are sampled
- $\{x, \lambda_1\}, \{x, \lambda_2\}, \dots, \{x, \lambda_n\}$.
4. This corresponds to having n sampling DMIS



Previous work – spectral rendering

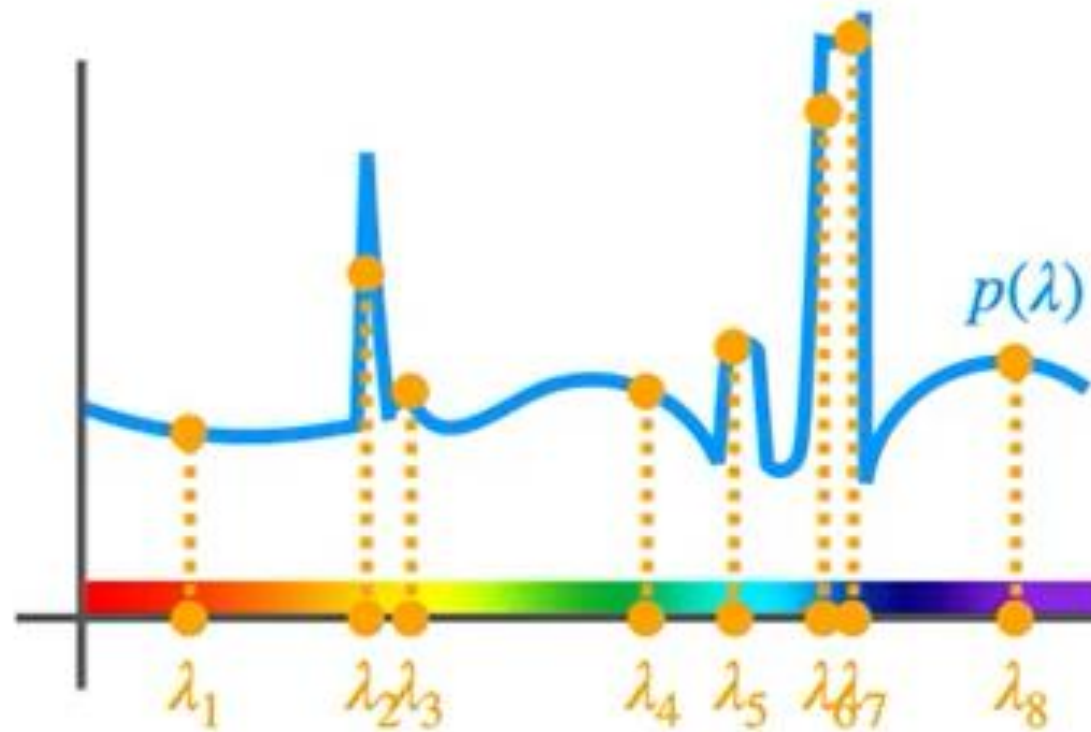
Alexander Wilkie, Sehera Nawaz, Marc Droske, Andrea Weidlich, and Johannes Hanika. 2014. Hero Wavelength Spectral Sampling.

Problem

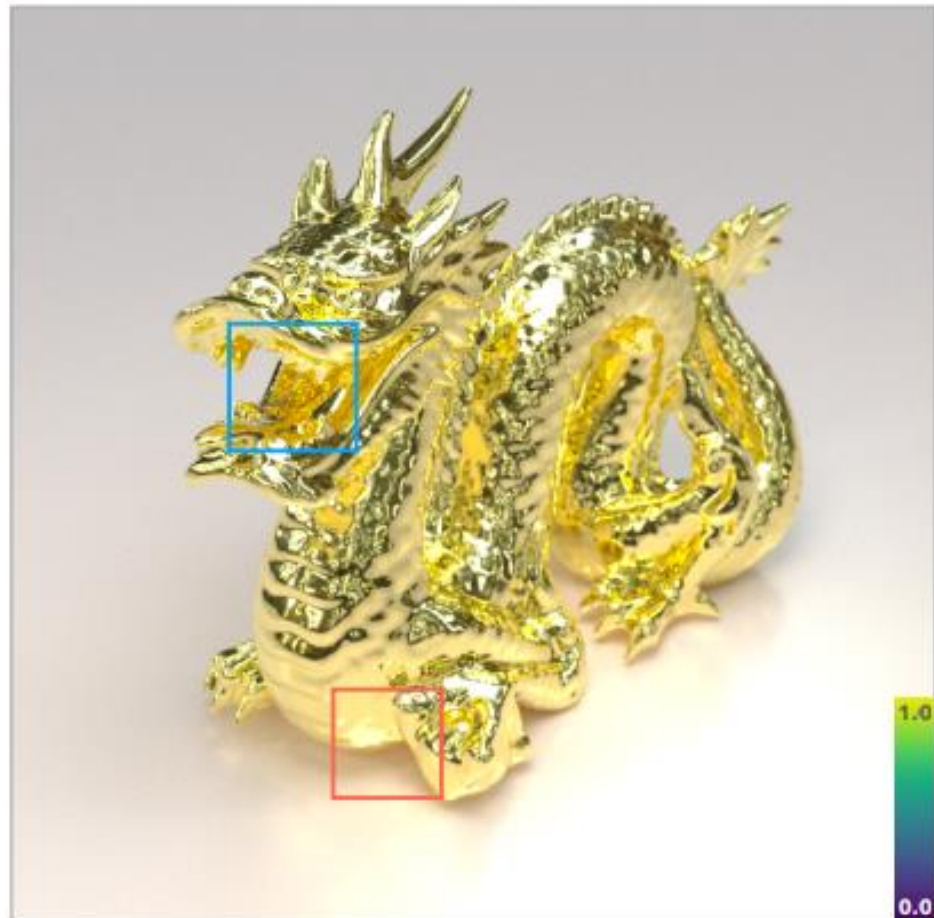
- Uniform wavelength spacing is sub-optimal for spectral power distributions that concentrate energy at a few peaks (e.g., fluorescent lights).



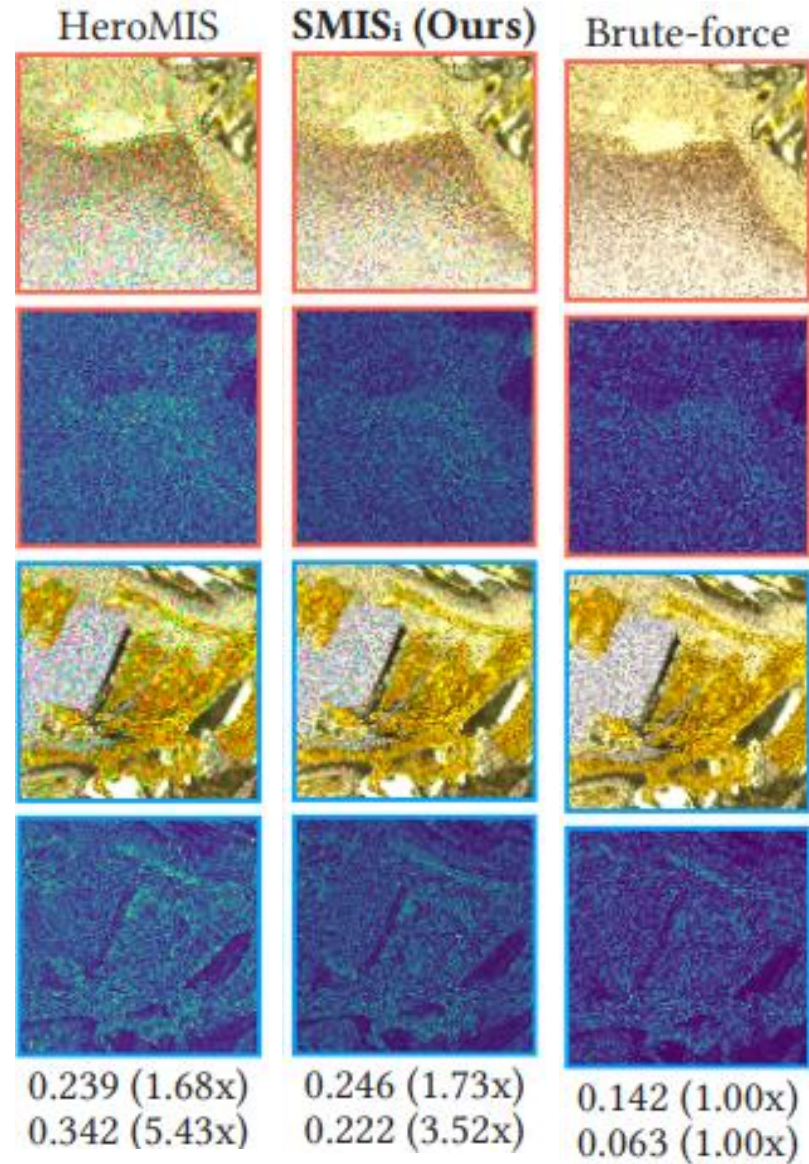
Spectral rendering- CMIS



Spectral rendering- CMIS



SMAPE
MSE



Summary

- Recap - Multiple Importance Sampling (**MIS**)
- Continuous Multiple Importance Sampling (**CMIS**)
- Stochastic Multiple Importance Sampling (**SMIS**)
- Application
 - Path reuse
 - Spectral rendering

Thank you